

Step 2 Show K depends only on Γ_{ij}^k 's and E, F, G .
functions

(sketch)

Notice: $(\bar{x}_{uu})_v = (\bar{x}_{uv})_u$

basis $\{\bar{x}_u, \bar{x}_v, N\}$

we know $x_{uu} = \Gamma_{11}^1 \bar{x}_u + \Gamma_{11}^2 \bar{x}_v + eN$

$$x_{uv} = \Gamma_{12}^1 \bar{x}_u + \Gamma_{12}^2 \bar{x}_v + fN$$

So: take deriv both sides (left w.r.t. v , right w.r.t. u) to get:

$$\begin{aligned} & \Gamma_{11}^1 \bar{x}_{uv} + \Gamma_{11}^2 \bar{x}_{vv} + eN_v + (\Gamma_{11}^1)_v \bar{x}_u + (\Gamma_{11}^2)_v \bar{x}_v + e_v N \\ &= \Gamma_{12}^1 \bar{x}_{uu} + \Gamma_{12}^2 \bar{x}_{vu} + fN_u + (\Gamma_{12}^1)_u \bar{x}_u + (\Gamma_{12}^2)_u \bar{x}_v + f_u N \end{aligned}$$

(\bar{x}_{uu})_v

(\bar{x}_{uv})_u

basis $\{\bar{x}_u, \bar{x}_v, N\}$

$$\begin{aligned} * \left\{ \begin{aligned} & \Gamma_{11}^1 \bar{x}_{uv} + \Gamma_{11}^2 \bar{x}_{vv} + e N_v + (\Gamma_{11}^1)_v \bar{x}_u + (\Gamma_{11}^2)_v \bar{x}_v + e_v N \\ & = \Gamma_{12}^1 \bar{x}_{uu} + \Gamma_{12}^2 \bar{x}_{vu} + f N_u + (\Gamma_{12}^1)_u \bar{x}_u + (\Gamma_{12}^2)_u \bar{x}_v + f_u N \end{aligned} \right. \end{aligned}$$

Now: replace \bar{x}_{uv} and \bar{x}_{vu} with respective Christoffel symbol

expansions and replace N_u with $a_{11} \bar{x}_u + a_{21} \bar{x}_v$,

N_v with $a_{12} \bar{x}_u + a_{22} \bar{x}_v \dots$ so everything is

in terms of basis $\{\bar{x}_u, \bar{x}_v, N\}$.

↳ unique expression of vectors.

Collect up like terms....

Equation * becomes: (sketch!)

P, Q, R, X, Y, Z each a big comb. of $\Gamma_{ij}^k, a_{ij}, e, f$

$$\begin{aligned} (P) \bar{x}_u + (Q) \bar{x}_v + (R) N \\ = (X) \bar{x}_u + (Y) \bar{x}_v + (Z) N \end{aligned}$$

By uniqueness of expression, we have

Turns out:

$$\textcircled{a} \quad \left\{ \begin{array}{l} Q = \Gamma_{11}^1 \Gamma_{21}^2 + \Gamma_{11}^2 \Gamma_{22}^2 + ea_{22} + (\Gamma_{11}^2)_v \\ Y = \Gamma_{12}^1 \Gamma_{11}^2 + \Gamma_{12}^2 \Gamma_{12}^2 + fa_{21} + (\Gamma_{12}^2)_u \end{array} \right. \text{equal}$$

Recall:
$$\begin{bmatrix} a_{11} & a_{21} \\ a_{21} & a_{22} \end{bmatrix} = - \begin{bmatrix} E & F \\ F & G \end{bmatrix}^{-1} \begin{bmatrix} e & f \\ f & g \end{bmatrix} \quad \left. \vphantom{\begin{bmatrix} a_{11} & a_{21} \\ a_{21} & a_{22} \end{bmatrix}} \right\} \text{Weingarten equations}$$

↖ local expression of dN_p

$$\text{So } a_{22} = \frac{fF - gE}{EG - F^2} \quad a_{21} = \frac{eF - fE}{EG - F^2}$$

In \textcircled{a} , put Γ_{ij}^k 's on one side and ea_{22} and fa_{21} on other,

and notice that $fa_{21} - ea_{22} = E \left(\frac{eg - f^2}{EG - F^2} \right) = EK$ to conclude:

CK

$$K = \frac{fa_{21} - ea_{22}}{E} = \frac{(\Gamma_{11}^2)_v - (\Gamma_{12}^2)_u + \Gamma_{11}^2 \Gamma_{22}^2 + \Gamma_{11}^1 \Gamma_{12}^2 - \Gamma_{12}^1 \Gamma_{11}^2 - \Gamma_{12}^2 \Gamma_{12}^1}{E}$$

the Gauss formula.

Conclusion! From Step 1, we know Γ_{ij}^k 's depend only on functions: E, F, G (ie. I_p)

← Gaussian curvature

Thus, from Step 2: we know K depends only on:

• Γ_{ij}^k 's and E, F, G, \dots ie. I_p

Therefore: K is an intrinsic invariant of S !

Gauss' Theorema Egregium

Corollary: If $\varphi: S_1 \rightarrow S_2$ is a local isometry, the $K_p = K_{\varphi(p)}$.