

Defn A map  $f: S_1 \rightarrow S_2$  is a local isometry at  $\bar{p}$

if there is an open set  $V \subset S_1$  about  $\bar{p}$  s.t.

$f|_V$  is an isometry b/w  $V$  and  $f(V)$ .

(isometry  $\Rightarrow$  local isometry)

local isometry  $\not\Rightarrow$  isometry ...  
similar for diffeos)

doesn't necessarily cover  
all of  $S_1$

Prop Spz  $(\bar{x}, u)$  is a parametrization of  $S_1$ . Then

$f: S_1 \rightarrow S_2$  is a local isometry at all points  $\bar{p}$  in

$\bar{x}(u)$  if and only if

$$E(\bar{p}) = df_p(\bar{x}_u) \cdot df_p(\bar{x}_u)$$

$$F(\bar{p}) = df_p(\bar{x}_u) \cdot df_p(\bar{x}_v)$$

$$G(\bar{p}) = df_p(\bar{x}_v) \cdot df_p(\bar{x}_v).$$

dot product  
preserved

proof: follows directly from definition of local isometry

and fact that dot product is linear ~~to linear~~

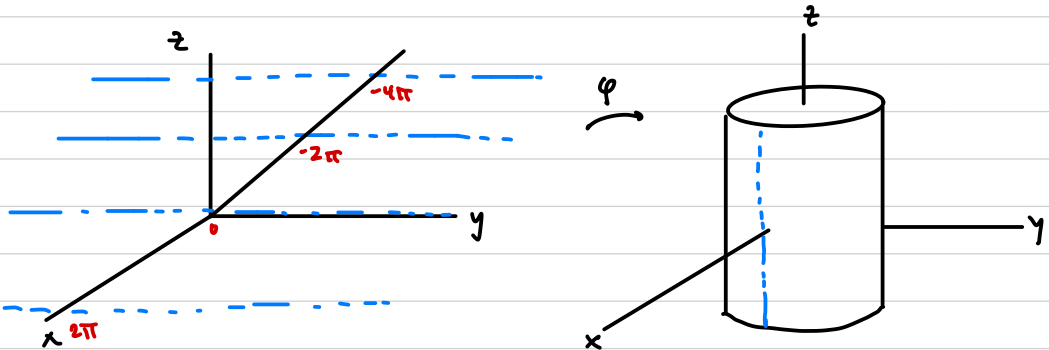
in both terms:  $(c\bar{x}_u + d\bar{x}_v) \cdot (g\bar{x}_u + h\bar{x}_v)$

(exercise)

$$\begin{aligned} &= cd\bar{x}_u \cdot \bar{x}_u + (ch + dg)\bar{x}_u \cdot \bar{x}_v + dh\bar{x}_v \cdot \bar{x}_v \\ &= \text{etc} \end{aligned}$$

Ex  $xy$ -plane and cylinder are locally isometric.

$$\varphi(x, y, 0) = (\cos x, \sin x, y)$$



Consider charts  $\bar{x}(u, v) = (u, v, 0)$ ,  $0 < u < 2\pi$ ,  $v \in \mathbb{R}$

and  $\bar{y}(s, t) = (\cos s, \sin s, t)$ ,  $0 < s < 2\pi$ ,  $t \in \mathbb{R}$ .

Notice that  $\bar{y}^{-1} \circ \varphi \circ \bar{x}(u, v) = \bar{y}^{-1}(\varphi(u, v, 0))$

$$= \bar{y}^{-1}(\cos u, \sin u, v)$$

$$= (u, v)$$

matrix representation  
of  $d\varphi_p$ , w/ bases

Thus, at all points  $\bar{p} = \bar{x}(u, v)$ ,  $d\varphi_{\bar{p}} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ .  $\{\bar{x}_u, \bar{x}_v\}$  and  $\{\bar{y}_s, \bar{y}_t\}$ .

So  $\bar{x}_u = 1\bar{x}_u + 0\bar{x}_v$ , thus  $d\varphi_{\bar{p}}(\bar{x}_u) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \bar{y}_s$

$1\bar{x}_u + 0\bar{x}_v$  (pointing to the vector  $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$ )

$1\bar{y}_s + 0\bar{y}_t$  (pointing to the vector  $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$ )

Similarly,  $d\varphi_{\bar{p}}(\bar{x}_v) = \bar{y}_t$

$\bar{x}(u, v) = (u, v, 0)$

Note:  $\bar{x}_u = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ ,  $\bar{x}_v = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$  so  $E(\bar{p}) = 1$   
 $F(\bar{p}) = 0$   
 $G(\bar{p}) = 1$

$y(s, t) = (\cos s, \sin s, t)$

and  $\bar{y}_s = \begin{bmatrix} -\sin s \\ \cos s \\ 0 \end{bmatrix}$ ,  $\bar{y}_t = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$  so  $d\varphi_p(\bar{x}_u) \cdot d\varphi_p(\bar{x}_u) = 1$   
 $d\varphi_p(\bar{x}_u) \cdot d\varphi_p(\bar{x}_v) = 0$   
 $d\varphi_p(\bar{x}_v) \cdot d\varphi_p(\bar{x}_v) = 1$

$d\varphi_p(\bar{x}_u)$  (pointing to  $\bar{y}_s$ )

$d\varphi_p(\bar{x}_v)$  (pointing to  $\bar{y}_t$ )

Thus, by proposition, plane and cylinder are locally isometric.