

Thm Sps. $\varphi: S_1 \rightarrow S_2$. Sps $\bar{w} \in T_p S$ is given by $\bar{\alpha}'(0)$.

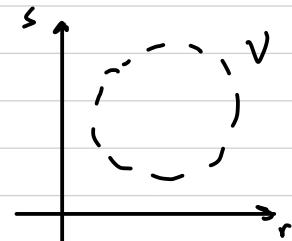
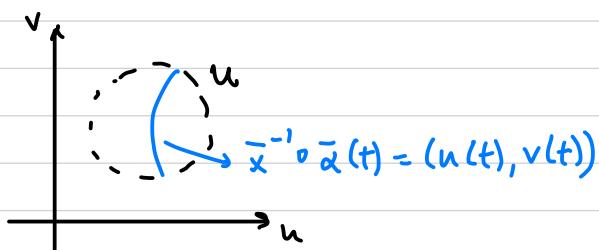
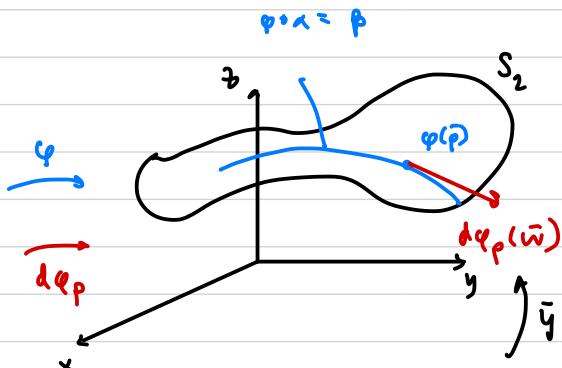
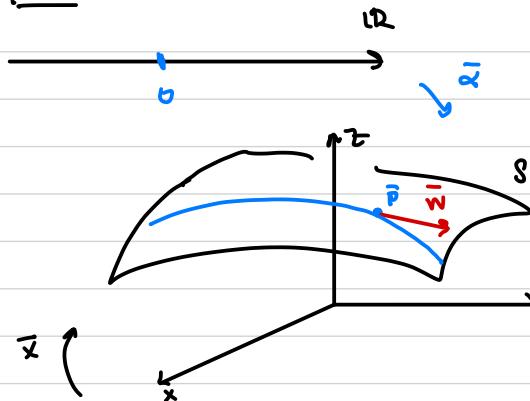
The map $d\varphi_p$ is linear and does not depend
on choice of $\bar{\alpha}$.



Remark: Thm also holds for $h: S_1 \rightarrow \mathbb{R}$...

$dh_p: T_p S \rightarrow \mathbb{R}$ is linear and doesn't depend
on choice of $\bar{\alpha}$. (exercise)

proof



let (\bar{x}, u) and (\bar{y}, v) be parametrizations about \bar{p}

and $\varphi(\bar{p})$. So

$$\{\bar{x}_u, \bar{x}_v\} \text{ and } \{\bar{y}_r, \bar{y}_s\}$$

are bases of $T_{\bar{p}}S_1$ and $T_{\varphi(\bar{p})}S_2$ respectively.

GOAL: Express $d\varphi_p$ in terms of $\{\bar{x}_u, \bar{x}_v\}$ and $\{\bar{y}_r, \bar{y}_s\}$

and show it is a linear map.

(In process, show $d\varphi_p(\bar{w})$ is independent of choice of $\bar{\alpha}$ used to define \bar{w} .)

In local coordinates given by \bar{x} and \bar{y} , suppose

$$\bar{y}^{-1} \circ \varphi \circ \bar{x}(u, v) = (\underbrace{\varphi_1(u, v)}, \underbrace{\varphi_2(u, v)})$$

$\uparrow r \quad \uparrow s$

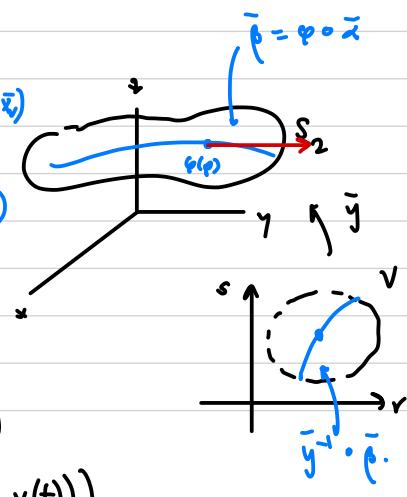
and $\bar{x}^{-1} \circ \bar{\alpha}(t) = (u(t), v(t))$.

(Recall: $\bar{\alpha}'(0) = \bar{w}$)

so $\bar{w} = u'(0)\bar{x}_u + v'(0)\bar{x}_v$

$\hookrightarrow \bar{\beta} = \varphi \circ \bar{\alpha}(t)$. (Recall $\bar{\beta}'(0) = d\varphi_p(\bar{w})$)

$$\begin{aligned} \text{So } \bar{y}^{-1} \circ \bar{\beta}(t) &= \bar{y}^{-1} \circ \varphi \circ \bar{\alpha}(t) \\ &= (\bar{y}^{-1} \circ \varphi \circ \bar{x}) \circ (\bar{x}^{-1} \circ \bar{\alpha})(t) \\ &= (\varphi_1(u(t), v(t)), \varphi_2(u(t), v(t))) \end{aligned}$$



deriv w.r.t. t

$$(\bar{y}^{-1} \cdot \bar{\beta})'(0) = \left(\frac{d\varphi_1}{dt}(0), \frac{d\varphi_2}{dt}(0) \right)$$

$$\begin{array}{c} \varphi_i \\ \diagdown \quad \diagup \\ u \quad v \\ | \quad | \\ t \quad t \end{array} \xrightarrow{\text{new notation}} = \frac{d\varphi_1(0)}{dt} \bar{e}_1 + \frac{d\varphi_2(0)}{dt} \bar{e}_2 \\ = \left[\frac{\partial \varphi_1}{\partial u} u'(0) + \frac{\partial \varphi_1}{\partial v} v'(0) \right] \bar{e}_1 + \left[\frac{\partial \varphi_2}{\partial u} u'(0) + \frac{\partial \varphi_2}{\partial v} v'(0) \right] \bar{e}_2 \\ * \qquad \qquad \qquad ** \end{array}$$

But $\bar{\beta}'(0)$ has same relationship to basis $\{\bar{y}_r, \bar{y}_s\}$

that $(\bar{y}^{-1} \cdot \bar{\beta})'(0)$ has to $\{\bar{e}_1, \bar{e}_2\}$. (similar for $\bar{\alpha}'(0)$ with basis $\{\bar{x}_u, \bar{x}_v\}$.)

So: $\bar{w} = \bar{\alpha}'(0)$ in terms of basis $\{\bar{x}_u, \bar{x}_v\}$ is: $\begin{bmatrix} u'(0) \\ v'(0) \end{bmatrix}$ and

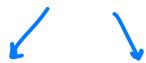
$$d\bar{\varphi}_p(\bar{w}) = \bar{\beta}'(0) = \begin{bmatrix} * \\ ** \end{bmatrix}$$

$d\bar{\varphi}_p(\bar{w})$ in
terms of basis
 $\{\bar{y}_r, \bar{y}_s\}$.

matrix of $d\bar{\varphi}_p$
in terms of
 $\{\bar{x}_u, \bar{x}_v\}$
and $\{\bar{y}_r, \bar{y}_s\}$

$$= \begin{bmatrix} \frac{\partial \varphi_1}{\partial u} & \frac{\partial \varphi_1}{\partial v} \\ \frac{\partial \varphi_2}{\partial u} & \frac{\partial \varphi_2}{\partial v} \end{bmatrix} \begin{bmatrix} u'(0) \\ v'(0) \end{bmatrix} \xrightarrow{\bar{\alpha}'(0)}$$

2-diml vector spaces!



Since $d\bar{\varphi}_p : T_p S_1 \rightarrow T_{\varphi(p)} S_2$ can be expressed

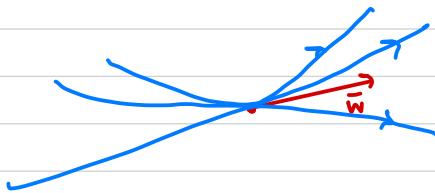
in terms of a matrix, it is a linear map.

Further: $d\varphi_p(\bar{w})$ depends only on coords of \bar{w}

w.r.t. $\{\bar{x}_u, \bar{x}_v\}$, namely $u'(0)$ and $v'(0)$

scalars

Thus $d\varphi_p(\bar{w})$ doesn't depend on choice of \bar{x} that represents \bar{w} .



many \bar{x} 's give same \bar{w} .

Note: matrix of $d\varphi_p$ is a 2×2 matrix b/c it

maps a 2-diml vector space $T_p S_1$ to a 2-dim'l vector space $T_{\varphi(p)} S_2$.